

Scaling points and reach for non-self-scaled barriers

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Outline

Conic optimization

- ▶ Conic programs
- ▶ Barriers
- ▶ Symmetric cones
- ▶ Scaling points

Scaling points and reach

- ▶ Scaling points as geodesic means
- ▶ Structures on primal-dual product
- ▶ Scaling points as orthogonal projections
- ▶ Reach property

Regular convex cones

Definition

A **regular** convex cone $K \subset \mathbb{R}^n$ is a closed convex cone having nonempty interior and containing no lines.

The **dual** cone

$$K^* = \{s \in \mathbb{R}^n \mid \langle x, s \rangle \geq 0 \quad \forall x \in K\}$$

of a regular convex cone K is also regular.

the dual cone is located in the dual vector space

Automorphisms

Definition

Let $K \subset \mathbb{R}^n$ be a regular convex cone. An **automorphism** of K is a linear map $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ such that $A[K] = K$.

an automorphism A of K induces an automorphism $B = A^{-T}$ of K^* which preserves the dual pairing:

$$\langle A(x), B(s) \rangle = \langle x, s \rangle$$

Conic programs

Definition

A **conic program** over a regular convex cone $K \subset \mathbb{R}^n$ is an optimization problem of the form

$$\min_{x \in K} \langle c, x \rangle : Ax = b.$$

every convex program can be transformed into a conic program

the **dual** program

$$\max_{s = -(A^T z - c) \in K^*} \langle b, z \rangle$$

is a conic program over the dual cone

primal-dual methods solve both problems simultaneously

Logarithmically homogeneous barriers

Definition (Nesterov, Nemirovski 1994)

Let $K \subset \mathbb{R}^n$ be a regular convex cone. A (self-concordant logarithmically homogeneous) **barrier** on K is a smooth function $F : K^\circ \rightarrow \mathbb{R}$ on the interior of K such that

- ▶ $F(\alpha x) = -\nu \log \alpha + F(x)$ (logarithmic homogeneity)
- ▶ $F''(x) \succ 0$ (convexity)
- ▶ $\lim_{x \rightarrow \partial K} F(x) = +\infty$ (boundary behaviour)
- ▶ $|F'''(x)[h, h, h]| \leq 2(F''(x)[h, h])^{3/2}$ (self-concordance)

for all tangent vectors h at x .

The homogeneity parameter ν is called the **barrier parameter**.

the Hessian F'' defines a **Riemannian metric** on the interior K° of K

Dual barrier

Theorem (Nesterov, Nemirovski 1994)

Let $K \subset \mathbb{R}^n$ be a regular convex cone and $F : K^\circ \rightarrow \mathbb{R}$ a barrier on K with parameter ν . Then the **Legendre transform**

$$F^*(p) = \sup_{x \in K} (\langle x, -p \rangle - F(x))$$

is a barrier on K^* with parameter ν .

the map $\mathcal{D} : x \mapsto p = -F'(x)$ is an **isometry** between K° and $(K^*)^\circ$ with respect to the **Hessian metrics** defined by F'' , $(F^*)''$

we have $\langle x, \mathcal{D}(x) \rangle = \nu$

Central path

consider the affine subspace $\mathcal{A} = \{(x, s) \mid Ax = b, s = c - A^T z\}$

the intersection $\mathcal{A} \cap (K \times K^*)$ is the set of primal-dual feasible pairs

the set $\{(x, s) \in \mathcal{A} \cap (K \times K^*)^\circ \mid \exists \mu > 0 : s = \mu D(x)\}$ is called the **central path** and can be parameterized by μ

note $\langle x, s \rangle = \mu \nu$ on the central path

the conditions

$$(x, s) \in \mathcal{A} \cap (K \times K^*), \quad \langle x, s \rangle = 0$$

are sufficient for optimality

hence the central path tends to an optimal solution for $\mu \rightarrow 0$

path-following methods make discrete steps in the vicinity of the central path while advancing towards the solution

Symmetric cones

Definition

A self-dual, homogeneous convex cone is called **symmetric**.

[Vinberg, 1960; Koecher, 1962] every symmetric cone is a product of the following irreducible symmetric cones:

- ▶ Lorentz (or second order) cone

$$L_n = \left\{ (x_0, \dots, x_{n-1}) \mid x_0 \geq \sqrt{x_1^2 + \dots + x_{n-1}^2} \right\}$$

- ▶ matrix cones $S_+(n)$, $H_+(n)$, $Q_+(n)$ of real, complex, or quaternionic hermitian positive semi-definite matrices
- ▶ Albert cone $O_+(3)$ of octonionic hermitian positive semi-definite 3×3 matrices

Jordan algebras

Definition

A commutative algebra J satisfying the condition

$$(x \bullet x) \bullet (x \bullet y) = x \bullet ((x \bullet x) \bullet y)$$

for all $x, y \in J$ is called a **Jordan algebra**.

A Jordan algebra is **Euclidean** if $\sum_{k=1}^n x_k \bullet x_k = 0$ implies $x_k = 0$ for all $k = 1, \dots, n$.

the symmetric cones can be represented exactly as the cones of squares $K = \{x \bullet x \mid x \in J\}$ of Euclidean Jordan algebras

Automorphisms and duality

for every $w \in J$ the map

$$P(w) : x \mapsto 2w \bullet (w \bullet x) - (w \bullet w) \bullet x$$

is a self-adjoint automorphism of K

the duality \mathcal{D} is represented by the inverse: $\mathcal{D}(x) = x^{-1}$

in particular, the central path condition $s = \mu \mathcal{D}(x)$ becomes

$$x \bullet s = \mu \cdot e$$

with e the identity element in J

Example: semi-definite matrix cone

$$X \bullet Y = \frac{XY + YX}{2}, \quad e = I, \quad \mathcal{D}(X) = X^{-1}$$

Programs over symmetric cones

conic programs over symmetric cones are **efficiently** solvable by **interior-point methods** [Nesterov, Nemirovski, 1994]

- ▶ linear programs (LP) over $\mathbb{R}_+^n \sim 10^6$ variables
- ▶ conic quadratic programs (CQP) over $L_n \sim 10^4$ variables
- ▶ semi-definite programs (SDP) over $S_+(n) \sim 10^2$ variables

structure can greatly increase tractable sizes

free (CLP, SDPT3, SeDuMi, SDPA, ...) and commercial (CPLEX, MOSEK, ...) solvers available

Self-scaled barriers

Definition

Let $K \subset \mathbb{R}^n$ be a regular convex cone, let K^* be its dual cone, let F be a self-concordant barrier on K with parameter ν , and let F^* be the dual barrier on K^* . Then F is called *self-scaled* if for every $x, w \in K^\circ$ we have

$$s = F''(w)x \in \text{int } K^*, \quad F^*(s) = F(x) - 2F(w) - \nu.$$

A cone K admitting a self-scaled barrier is called *self-scaled cone*.

Hauser, Güler, Lim, Schmieta 1998 – 2002:

- ▶ self-scaled cone \Leftrightarrow symmetric cone
- ▶ self-scaled barriers on products are sums of self-scaled barriers on irreducible components
- ▶ self-scaled barriers on irreducible cones are log-determinants

Scalings

let F be a self-scaled barrier on a symmetric cone

for every $(x, s) \in (K \times K^*)^\circ$ there exists a unique **scaling point** $w \in K^\circ$ such that

$$F''(w)x = s$$

equivalently, there exists a self-adjoint automorphism $A = P(w^{-1})$ of K with induced automorphism $B = A^{-T} = P(w)$ of K^* such that

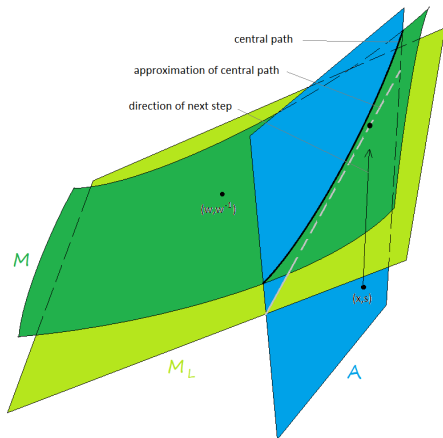
$$B(s) = A(x)$$

Nesterov-Todd type methods proceed from one primal-dual iterate (x, s) to the next by solving a linearized version of the system

$$[P(w^{-1})](x) \bullet [P(w)](s) = \mu \cdot e$$

while staying in $\mathcal{A} \cap (K \times K^*)^\circ$

Geometric interpretation



$$M = \{(x, s) \mid \exists \mu > 0 : s = \mu D(x)\}$$

M_L is a linear approximation of M at (w, w^{-1})

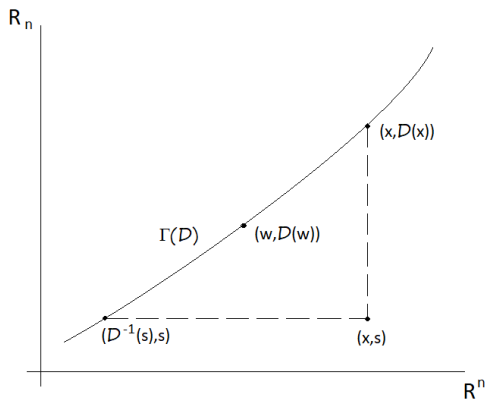
$$\dim \mathcal{A} = n, \dim M = n + 1$$

Generalization to non self-scaled barriers?

the geometric interpretation works independently of the self-scaled property

provided we find an adequate generalization of the scaling point w corresponding to a primal-dual pair (x, s)

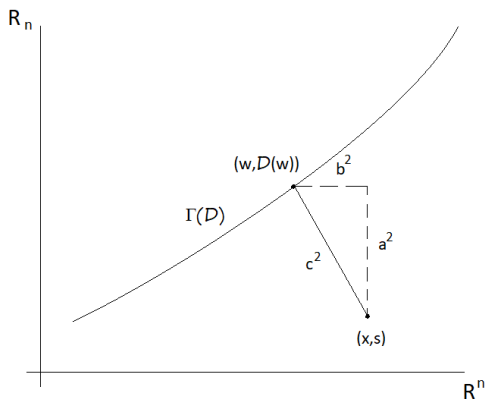
Scaling point as geodesic mean



the graph $\Gamma(\mathcal{D})$ of the duality map inherits the metric of F'' on K°
the point $(w, \mathcal{D}(w))$ on $\Gamma(\mathcal{D})$ is the geodesic mean between the
projections $(x, \mathcal{D}(x))$, $(\mathcal{D}^{-1}(s), s)$ of the primal-dual iterate (x, s)

Scaling point as nearest point

in order for the linear approximation to be accurate the scaling pair $(w, \mathcal{D}(w))$ has to be **close** to the current iterate



in the product metric on $(K \times K^*)^o$ we have also to compute geodesic lengths — difficult

Product of dual pair of spaces

Is there a better choice of a metric in $\mathbb{R}^n \times \mathbb{R}_n$?

neither the vector space \mathbb{R}^n nor its dual \mathbb{R}_n carry a canonical metric, only a family of equivalent metrics which all lead to the same flat affine connection

the **product** $\mathbb{R}^n \times \mathbb{R}_n$ has a lot more structure

- ▶ flat pseudo-Riemannian metric

$$G((x, p); (y, q)) = \frac{1}{2}(\langle x, q \rangle + \langle y, p \rangle)$$

- ▶ $\text{dist}((x, p); (y, q)) = \langle x - y, p - q \rangle$

- ▶ symplectic form $\omega((x, p); (y, q)) = \frac{1}{2}(\langle x, q \rangle - \langle y, p \rangle)$

$\mathbb{R}^n \times \mathbb{R}_n$ is a flat **para-Kähler space form**

Duality graph as Lagrangian submanifold

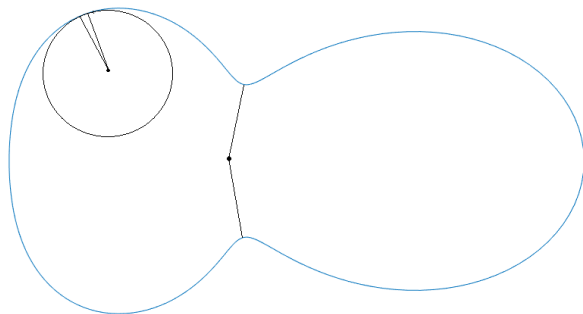
let \mathcal{D} be the duality map of a self-concordant barrier with parameter ν

- ▶ the duality graph $\Gamma(\mathcal{D})$ is a **Lagrangian submanifold** of $\mathbb{R}^n \times \mathbb{R}_n$
- ▶ the metric on $\Gamma(\mathcal{D})$ equals ν times the submanifold metric induced by $\mathbb{R}^n \times \mathbb{R}_n$
- ▶ the curvature of $\Gamma(\mathcal{D})$ is globally bounded by $\sqrt{\nu}$

similar assertions hold when passing to the product $\mathbb{R}P^{n-1} \times \mathbb{R}P_{n-1}$ of projective spaces

for self-scaled barriers in the projective setting the scaling pair is indeed the nearest point in the pseudo-Riemannian metric of the para-Kähler space

Existence of nearest point



obstacles for the existence of a nearest point:

- ▶ global: points far away on the submanifold are close in ambient space
- ▶ local: curvature of the manifold

Reach property

Definition (Federer 1959)

Let $A \subset E$ be a subset of a Euclidean space.

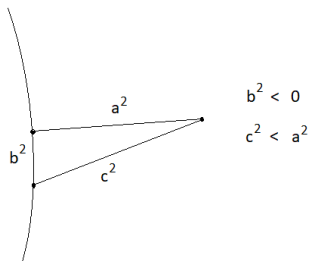
A **unique closest point** of A is a point $x \in E$ such that there exists a unique point $a \in A$ with $\|x - a\| = d(x, A)$.

The **reach** of a point $a \in A$ is the largest $r \geq 0$ such that the open ball $B_r^o(a)$ around a consists of unique closest points.

The **reach** of A is the infimum over $a \in A$ of the reach of a .

- ▶ A has infinite reach if and only if A is closed convex
- ▶ smooth compact connected submanifolds have positive reach
- ▶ the reach of a is continuous on A
- ▶ for smooth manifolds A the inverse of the reach is bounded from below by the curvature of A
- ▶ can be generalized to subsets of Riemannian manifolds

Reach in pseudo-Riemannian space forms



Definition

Let $M \subset \mathcal{M}$ be **negative definite** of maximal dimension.

A **unique closest point** of M is a point $x \in \mathcal{M}$ such that there exists a unique point $z \in M$ with $(a; x) = \inf_{z' \in M} d(x, z')$.

The **reach** of a point $z \in M$ is the largest $r \geq 0$ such that the open ball $B_r^o(z)$ around z in the normal submanifold to M at z consists of unique closest points.

The **reach** of M is the infimum over $z \in M$ of the reach of z .

Main result

Theorem

Let $K \subset \mathbb{R}^n$ be a regular convex cone and F a self-concordant barrier on K with parameter ν .

The corresponding Lagrangian submanifold $\Gamma(\mathcal{D}) \subset \mathbb{R}^n \times \mathbb{R}_n$ has reach $\nu^{-1/2}$.

The corresponding Lagrangian submanifold in $\mathbb{R}P^{n-1} \times \mathbb{R}P_{n-1}$ has reach $\arccos \sqrt{\frac{\nu-1}{\nu}}$.

in particular, in a tube of corresponding radius scaling points defined via the nearest point on the graph $\Gamma(\mathcal{D})$ exist and are unique

Thank you