

# LYAPUNOV STABILITY OF A SINGULARLY PERTURBED SYSTEM OF TWO CONSERVATION LAWS

– talk –

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The singular perturbation techniques occurred at the beginning of the 20th century (see [1]). The development of this method led to the efficient use in various fields in mathematical physics and engineering, for instance, fluid mechanics, fluid dynamics, elasticity, quantum mechanics, chemical-reactor, aerodynamics etc. (see [2] for a survey). Lyapunov methods are usually used for stability analysis of dynamical systems. This is also true for those dynamics with a small perturbation parameter. In the work of [3], a quadratic-type Lyapunov function has been investigated for a singularly perturbed finite-dimensional nonlinear system.

In our work, systems modelled by singularly perturbed partial differential equations (PDEs) are considered. More precisely a class of systems of two conservation laws with a small perturbation parameter  $\epsilon$  is investigated. By setting  $\epsilon = 0$  the singularly perturbed system is divided as two subsystems: the reduced and boundary-layer systems. Each of the two systems has a Lyapunov function and is asymptotically stable under suitable boundary conditions. For a sufficiently small perturbation parameter, the stability of the singularly perturbed system of conservation laws can be obtained by a Lyapunov function which is given by a convex combination of the Lyapunov function of the reduced and boundary-layer systems.

The work is organized as 4 parts. The first part introduces the singularly perturbed system of conservation laws. The second part presents the stability of the reduced and boundary-layer systems. The third part shows the stability for the overall singularly perturbed system. In the last part an illustrative example is provided to show the main result.

## REFERENCES

- [1] P. Kokotovic, and H.K. Khalil, and O'R. John. Singular perturbation methods in control: analysis and design. Academic Press, 1986.
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- [3] A. Saberi and H.K. Khalil. Quadratic-type Lyapunov Functions for Singularly Perturbed Systems. IEEE Transactions on Automatic Control, 1984.

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